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economy (Diesendorf, 2014, p. 143) and decrease of overall carbon intensity of the energy system. It will be shown below that over the next few decades, up to the mid-21st century, mitigation costs do hinder economic growth, but that this growth reduction is compensated later on by the having avoided negative impacts of climate change on the economy; see also Kovalevsky and Hasselmann (2014, Fig. 2).

The companion paper, Part 2, complements the model by introducing carbon capturing and storing (CCS) technologies and control of deforestation, as well as increasing photosynthetic biomass sinks as a method of controlling atmospheric CO₂ and consequently the intensity and frequency of climate change related damages.

Our Coupled Climate–Economy–Biosphere (CoCEB) model is not intended to give a detailed quantitative description of all the processes involved, nor to make specific predictions for the latter part of this century. It is a reduced-complexity model that tries to incorporate the climate–economy–biosphere interactions and feedbacks with the minimum amount of variables and equations needed. We merely wish to trade realism for greater flexibility and transparency of the dynamical interactions between the different variables. The need for a hierarchy of models of increasing complexity is an idea that dates back – in the climate sciences – to the beginnings of numerical modeling (e.g. Schneider and Dickinson, 1974), and has been broadly developed and applied since (Ghil, 2001, and references therein). There is an equivalent need for such model hierarchy to deal with the higher-complexity problems at the interface of the biogeophysical-biogeochemical climate sciences and of socio-economic policy.

The CoCEB model lies toward the highly idealized end of such a hierarchy: it takes an integrated assessment approach to simulating global change. By using an endogenous economic growth module with physical and human capital accumulation, this paper considers the sustainability of economic growth, as economic activity intensifies greenhouse gas emissions that in turn cause economic damage due to climate change (Stern, 2007; Nordhaus, 2008; Dell et al., 2014 and the references therein).

As different types of fossil fuels produce different volumes of CO₂ in combustion, the dynamics of fossil fuel consumption – that is, the relative shares of coal, oil, and nat-

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5 ural gas – has to be taken into account when calculating the future dynamics of CO₂ emission (see also, Akaev, 2012). These shares are not known at this time (Akaev, 2012), nor is it easy to predict their evolution. In order to describe the dynamics of hydrocarbon-based energy share into the global energy balance of the 21st century and their replacement with renewable energy sources we use, following Sahal (1981), logistic functions (see also, Probert et al., 2004, p. 108, and references therein). This is a novel approach with respect to most other integrated assessment modeling studies in the climate change mitigation literature, which often assume an unrealistic approach of fixed, predictable technological change, independent of public policy, as well as the treatment of investment in abatement as a pure loss (Stanton et al., 2009). Technology change in these IAMs is modeled in a simple way by using an autonomous energy efficiency improvement (AEEI) parameter that improves the energy efficiency of the economy by some exogenous amount overtime: see, for instance, Bosetti et al.'s (2006, 2009) World Induced Technical Change Hybrid (WITCH) model and van Vuuren et al.'s (2006) Integrated Model for the Assessment of the Global Environment (IMAGE) model. However, the use of AEEI ignores the causes that influence the evolution of technologies (Lucas, 1976; Popp et al., 2010 and references therein). Even though this shortcoming can be remedied by including endogenous technological change in IAMs either through direct price-induced, research and development-induced, or learning-induced approaches (see Popp et al., 2010 for details), there is no accord in the climate change mitigation literature regarding a single best approach (Grubb et al., 2002; Popp et al., 2010).

25 Various climate change mitigation policy measures are considered. While many integrated assessment models treat abatement costs merely as an unproductive loss of income (e.g. Nordhaus and Boyer, 2000; Nordhaus, 2007, 2008, 2010, 2013), we consider abatement activities also as an investment in overall energy efficiency of the economy and decrease of overall carbon intensity of the energy system. The paper shows that these efforts help to reduce the volume of industrial carbon dioxide emissions, lower temperature deviations, and lead to positive effects in economic growth.

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are represented in this highly idealized model by the factor β_1 , which is assumed to take values between 1.1 and 3.4 (Greiner and Semmler, 2008, p. 62); in this study, it was assumed that $\beta_1 = 3.3$. The parameter $\xi = 0.23$ captures the fact that part of the warmth generated by the greenhouse effect is absorbed by the oceans and transported from their upper layers to the deep sea (Greiner and Semmler, 2008). The other parameters have standard values that are listed in Table 1.

At equilibrium, that is for $dT/dt = 0$, Eq. (1) gives an average SAT of 14°C for the pre-industrial GHG concentration, i.e. for $C = \hat{C}$. Doubling the CO_2 concentration in Eq. (1) yields an increase of about 3.3°C in equilibrium temperature, to 17°C . This increase lies within the range of IPCC estimates, between 1.5 and 4.5°C (Charney et al., 1979; IPCC, 2001, p. 67, 2013) with a best estimate of about 3.0°C (IPCC, 2007, p. 12).

We represent the evolution C of the concentration of CO_2 in the atmosphere, following Uzawa (2003) and Greiner and Semmler (2008), as

$$\frac{dC}{dt} = \beta_2 E_Y - \mu_o (C - \hat{C}), \quad (2)$$

where E_Y is industrial CO_2 emissions. The excess C above pre-industrial level is reduced by the combined effect of land and ocean sinks. The inverse μ_o of the atmospheric lifetime of CO_2 is estimated in the literature to lie within an uncertainty range that spans 0.005 – 0.2 (IPCC, 2001, p. 38); we take it here to equal $\mu_o = 1/120 = 0.0083$, i.e. closer to the lower end of the range (Nordhaus, 1994a, p. 21; IPCC, 2001, p. 38). The fact that a certain part of GHG emissions is taken up by the oceans and does not remain in the atmosphere is reflected in Eq. (2) by the parameter β_2 .

2.2 Economy module

In Greiner (2004) and Greiner and Semmler (2008) the per capita gross domestic product (GDP), Y , is given by a modified version of a constant-return-to scale Cobb–Douglas production function (Cobb and Douglas, 1928),

$$Y = AK^\alpha H^{1-\alpha} D(T - \hat{T}). \quad (3)$$

For physical capital to increase, $dK/dt > 0$, the parameters must satisfy the inequality $0 < [\tau(1 + \tau_b) + c(1 - \tau)] < 1$. Now, proceeding as above for K , we assume that the per capita human capital H evolves over time as

$$\frac{dH}{dt} = \varphi \left\{ AK^\alpha H^{1-\alpha} D(T - \hat{T}) [1 - \tau(1 + \tau_b) - c(1 - \tau)] \right\} - (\delta_H + n)H, \quad (10)$$

here $\varphi > 0$ is a coefficient that determines how much any unit of investment contributes to the formation of the stock of knowledge and δ_H gives the depreciation of knowledge.

Note that we take, as a starting point, the Solow–Swan approach (Solow, 1956; Swan, 1956; Greiner and Semmler, 2008), in which the share of consumption and saving are given. We do this because we want to focus on effects resulting from climate change, which affect production as modeled in Eqs. (3)–(10) and, therefore, neglect effects resulting from different preferences.

Our formulation assumes, furthermore, that government spending, except for abatement, does not affect production possibilities. Emissions of CO_2 are a byproduct of production and hence are a function of per capita output relative to per capita abatement activities. This implies that a higher production goes along with higher emissions for a given level of abatement spending. This assumption is frequently encountered in environmental economics (e.g. Smulders, 1995). It should also be mentioned that the emission of CO_2 affect production indirectly by affecting the climate of the Earth, which leads to a higher SAT and to an increase in the number and intensity of climate-related disasters (see, e.g. Emanuel, 2005; Min et al., 2011).

2.3 Industrial CO_2 emissions

In Greiner (2004) and Greiner and Semmler (2008), emissions E_Y are formally described, as a function of the production Y , by

$$\left(\frac{aY}{G_E} \right)^Y = \left(\frac{aY}{\tau_b \tau Y} \right)^Y = \left(\frac{a}{\tau_b \tau} \right)^Y, \quad (11)$$

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here $\gamma > 0$ is a constant and $a > 0$ a technology index that describes how polluting a given technology is. Note that Eq. (11) is defined only for τ_b different from zero; hence, it does not consider a no-abatement or BAU scenario. Moreover, Eq. (11) also gives constant emissions over time even when the economic activity is changing, which is unrealistic. Here, we use instead a formulation of emissions E_Y that vary over time and in which we can let abatement be zero.

Specifically, we use the Kaya–Bauer identity (Kaya, 1990; Bauer, 2005) that breaks down CO_2 emissions E_Y (in GtC yr^{-1}) into a product of five components: emissions per unit of energy consumed (carbon intensity of energy), energy use per unit of aggregate GDP (energy intensity), per capita GDP, human population, and carbon emission intensity, as shown below:

$$\begin{aligned} E_Y &= \left(\frac{E_{\text{tot}}}{\text{energy}} \right) \left(\frac{\text{energy}}{\bar{Y}} \right) \left(\frac{\bar{Y}}{L} \right) L \left(\frac{E_Y}{E_{\text{tot}}} \right) \\ &= c_c e_c Y L \kappa_{\text{CCS}} \\ &= \sigma Y L \kappa_{\text{CCS}}. \end{aligned}$$

Here \bar{Y} is aggregate GDP, $Y = (\bar{Y}/L)$ is per capita GDP, L is the human population, $c_c = E_{\text{tot}}/\text{energy}$ is the carbon intensity of energy, $e_c = \text{energy}/\bar{Y}$ is the energy intensity, $c_c e_c = E_{\text{tot}}/\bar{Y} = \sigma$ is the ratio of industrial carbon emissions to aggregate GDP or the economy carbon intensity, $E_Y/E_{\text{tot}} = \kappa_{\text{CCS}}$ is the fraction of emissions that is vented to the atmosphere and involves CCS.

The E_Y level also depends on abatement activities, as invested in the increase of overall energy efficiency in the economy and decrease of overall carbon intensity of the energy system. The case of $\tau_b = 0$ in Eq. (5) corresponds to unabated emissions, i.e. BAU. Emissions are reduced as the abatement share increases. Taking the natural logarithms and differentiating both sides of the Kaya–Bauer identity yields

$$\frac{dE_Y}{dt} = [g_\sigma + g_Y + n + g_{\text{CCS}}] E_Y, \quad (12)$$

gas – should be taken into account when calculating the future dynamics of CO₂ emission. Since these shares are not known at this time, we assume a logistic function for describing a reduction of the carbon intensity of energy c_c , in tons of carbon/tons of reference fuel (tCTRF⁻¹), throughout the 21st century (Akaev, 2012),

$$c_c = c_{-\infty} + \frac{a_c}{1 + r \exp(-\psi t)}, \quad (14)$$

with $a_c > 0$ a constant.

Thus the carbon intensity σ , which is technology-dependent and represents the trend in the CO₂-output ratio, can now be given by the product of the energy intensity e_c in Eq. (13) and the carbon intensity of energy c_c in Eq. (14), thus:

$$\sigma = f_c \left[1 - \frac{r \exp(\psi t)}{1 + r(\exp(\psi t) - 1)} \right] \left[c_{-\infty} + \frac{a_c}{1 + r \exp(-\psi t)} \right]. \quad (15)$$

We can now calculate the de-carbonization of the economy, i.e. the declining growth rate of σ , by taking the natural logarithms of Eq. (15) and getting the derivative with respect to time:

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$$g_{\sigma} = \frac{f_c}{e_c} \left[\frac{[\psi r \exp(\psi t)][1 + r(\exp(\psi t) - 1)] - [\psi r^2 \exp(\psi t)]}{[1 + r(\exp(\psi t) - 1)]^2} \right] + \frac{1}{c_c} \left[\frac{a_c \psi r \exp(-\psi t)}{[1 + r \exp(-\psi t)]^2} \right]. \quad (16)$$

In a similar way as Eq. (16) was derived from Eq. (15), the growth rate g_Y of per capita output is obtained from Eq. (3) as

$$\frac{1}{Y} \frac{dY}{dt} = \frac{\alpha}{K} \frac{dK}{dt} + \frac{(1-\alpha)}{H} \frac{dH}{dt} + \frac{1}{D} \frac{dD}{dT} \frac{dT}{dt},$$

or,

$$g_Y = \alpha g_K + (1-\alpha)g_H + \frac{1}{D} \frac{dD}{dT} \frac{dT}{dt}, \quad (17)$$

with g_K the per capita physical capital growth and g_H the per capita human capital growth.

Human population evolves; cf. Golosovsky (2010), as

$$\frac{dL}{dt} = nL \{1 - \exp[-(L/L(1990))]\}, \quad (18)$$

where n is the population growth rate as given in Eq. (8). Equation (18) yields $L = 9 \times 10^9$ people in the year $t = 2100$. This value is consistent with the 2100 population projections of scenarios in the literature (e.g. van Vuuren et al., 2012, Table 3).

Damage function

The damage function D gives the decline in Y , the global GDP, which results from an increase of the temperature T above the pre-industrial temperature \hat{T} . Nordhaus (1994a) formulates it as

2.6 Abatement share

The abatement costs of several IAMs tend to cluster in the range of about 1–2 % of GDP as the cost of cutting carbon emissions from baseline by 50 % in the period 2025–2050, and about 2.5–3.5 % of GDP as the cost of reducing emissions from baseline by about 70 % by 2075–2100 (Boero et al., 1991; Cline, 1992, p. 184; Boero, 1995; Clarke et al., 1996; Tol, 2010, p. 87, Fig. 2.2) with an increasing dispersion of results as higher emission reduction targets are set (Boero et al., 1991).

Using the definition of abatement in Eq. (5) and the GDP evolution in Eq. (3), we obtain an abatement share that gives an abatement cost equivalent to 1 % of GDP by 2050 to be

$$\frac{G_E}{Y} = \tau_b \tau = 0.01 \Rightarrow \tau_b = 0.05. \quad (20)$$

Similarly, the abatement share giving an abatement cost equivalent to 2 % of GDP by 2050 is $\tau_b = 0.1$. We take, as our lower abatement share, the average $\tau_b = 0.075$ of the two abatement shares that give an abatement cost equivalent to 1.5 % of GDP by 2050.

Next, we choose the abatement efficiency parameter $\alpha_\tau = 1.8$ such that, for the path corresponding to $\tau_b = 0.075$, carbon emissions reduction from baseline is about 50 % by 2050. Our scenario corresponding to $\tau_b = 0.075$ also happens to mimic the RCP6.0 by 2100 (Fujino et al., 2006; Hijioka et al., 2008; IPCC, 2013). For the other non-BAU scenarios, we choose abatement shares of $\tau_b = 0.11$ and 0.145, such that an emissions reduction of 50 % or more from baseline by 2050 and beyond gives a reduction in GDP of 2.2 and 2.9 %, respectively; the scenario given by $\tau_b = 0.11$ also mimics RCP4.5 (Clerke et al., 2007; Wise et al., 2009; IPCC, 2013). Note that the abatement shares in Greiner (2004) and Greiner and Semmler (2008), which use Eq. (11), are about 10 times lower than the ones chosen here.

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2.7 Summary formulation of CoCEB

Our coupled CoCEB model is described by Eqs. (1), (2), (9), (10) and (12). The model describes the temporal dynamics of five variables: per capita physical capital K , per capita human capital H , the average global surface air temperature T , the CO_2 concentration in the atmosphere C , and industrial CO_2 emissions E_Y . The other variables are connected to these five independent variables by algebraic equations. In Part 2, a supplementary equation will be added for the biomass. The equations are grouped for the reader's convenience below:

$$\frac{dK}{dt} = A [1 - \tau(1 + \tau_b) - c(1 - \tau)] K^\alpha H^{1-\alpha} D(T - \hat{T}) - (\lambda_K + n)K, \quad (21a)$$

$$\frac{dH}{dt} = \varphi \left\{ A [1 - \tau(1 + \tau_b) - c(1 - \tau)] K^\alpha H^{1-\alpha} D(T - \hat{T}) \right\} - (\lambda_H + n)H, \quad (21b)$$

$$\frac{dT}{dt} = \frac{(1 - \alpha_T)Q}{4c_h} - \frac{\varepsilon\sigma_T\tau_a T^4}{c_h} + \frac{\beta_1(1 - \xi)}{c_h} 6.3 \ln \left(\frac{C}{\hat{C}} \right), \quad (21c)$$

$$\frac{dC}{dt} = \beta_2 E_Y - \mu_o(C - \hat{C}), \quad (21d)$$

$$\frac{dE_Y}{dt} = [g_\sigma + g_Y + n] E_Y. \quad (21e)$$

The parameter values used in the model are as described in the text above and in Table 1 below. They have been chosen according to standard tables and previous papers.

3 Numerical simulations and abatement results

In the following, we confine our investigations to the transition path for the 110 years from the baseline year 1990 to the end of this century. We consider four scenarios with an aggregate CO_2 concentration larger than or equal to the pre-industrial

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Now, according to the United Nations Framework Convention on Climate Change (UNFCCC, 1992), the average global SAT should not exceed its pre-industrial level by more than 2 °C. This SAT target means that global efforts to restrict or reduce CO₂ emissions must aim at an atmospheric CO₂ concentration of no more than 1171.5 Gt C.

This CO₂ target can be achieved if carbon emissions are reduced to no more than 3.3 GtCyr⁻¹, or nearly half relative to the 1990 level of 6 GtCyr⁻¹ (Akaev, 2012). This goal is met, in our highly simplified model, by the path with the highest abatement share of the four, $\tau_b = 0.145$. From Table 2 and Fig. 1, we notice that this level of investment in the increase of overall energy efficiency of the economy and decrease of overall carbon intensity of the energy system enable emissions to decrease to 2.5 GtCyr⁻¹ by year 2100 (Fig. 1a), about a 58 % drop below the 1990 emissions level. This emissions drop enables the deviation from pre-industrial SAT to reach no higher than 2 °C by year 2100 (Fig. 1c).

The per capita abatement costs $G_E = \tau_b X = \tau_b \tau Y$ from Eq. (5) and the damage costs $(1 - D)Y$ from Eq. (19) for the various emission reduction paths are given in Table 3 for the year 2100. From the table we notice that, generally, the more one invests in abatement, the more emissions are reduced relative to baseline and the less the cost of damages from climate change. From Tables 2 and 3, we notice that limiting global average SAT to about 2 °C over pre-industrial levels would require an emissions reduction of 92 % from baseline by 2100, at a per capita cost of USD₁₉₉₀ 990, which translates to 2.9 % of per capita GDP. Although attaining the 2 °C goal comes at a price, the damages will be lower all along and the GDP growth better than for BAU starting from the cross-over year 2058.

Recall, moreover, that the benefits of GHG abatement are not limited to the reduction of climate change costs alone. A reduction in CO₂ emissions will often also reduce other environmental problems related to the combustion of fossil fuels. The size of these so-called secondary benefits is site-dependent (IPCC, 1996b, p. 183), and it is not taken into consideration as yet in the CoCEB model.

5 Conclusions and way forward

5.1 Summary

In this paper, we introduced a simple coupled climate–economy (CoCEB) model with the goal of understanding the various feedbacks involved in the system and also for use by policy makers in addressing the climate change challenge. In this Part 1 of our study, economic activities are represented through a Cobb–Douglas output function with constant returns to scale of the two factors of production: per capita physical capital and per capita human capital. The income after tax is used for investment, consumption, and abatement. Climate change enters the model through the emission of GHGs arising in proportion to economic activity. These emissions accumulate in the atmosphere and lead to a higher global mean surface air temperature (SAT). This higher temperature then causes damages by reducing output according to a damage function. The CoCEB model, as formulated here, was summarized as Eqs. (21a)–(21e) in Sect. 2.7.

Using this model, we investigated in Sect. 3 the relationship between investing in the increase of overall energy efficiency of the economy and decrease of overall carbon intensity of the energy system through abatement activities, as well as the time evolution, from 1990 to 2100, of the growth rate of the economy under threat from climate change–related damages. The CoCEB model shows that taking no abatement measures to reduce GHGs leads eventually to a slowdown in economic growth; see also Kovalevsky and Hasselmann (2014, Fig. 2).

This slowdown implies that future generations will be less able to invest in emissions control or adapt to the detrimental impacts of climate change (Krakauer, 2014). Therefore, the possibility of a long-term economic slowdown due to lack of abating climate change (Kovalevsky and Hasselmann, 2014) heightens the urgency of reducing GHGs by investing in low-carbon technologies, such as electric cars, biofuels, CO₂ capturing and storing (CCS), renewable energy sources (Rozenberg et al., 2014), and technology for growing crops (Wise et al., 2009). Even if this incurs short-term economic costs, the transformation to a de-carbonized economy is both feasible and affordable accord-

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5 uals over a finite time horizon. The Pontryagin Maximum Principle (Pontryagin et al., 1964; Hestenes, 1966; Sethi and Thompson, 2000) is used to find the necessary optimality conditions for the *finite-horizon* control problem. The Maximum Principle for *infinite-horizon* control problems is presented in Michel (1982), Seierstadt and Syd-
saeter (1987), Aseev and Kryazhimskiy (2004, 2007), and Maurer et al. (2013). For
a modern theory of infinite–horizon control problems the reader is referred to Lykina
et al. (2008). The determination of an optimal abatement path along the lines above
will be the object of future work.

10 Concerning the damage function, Stern (2007) states that “Most existing IAMs also
omit other potentially important factors – such as social and political instability and
cross-sector impacts. And they have not yet incorporated the newest evidence on
damaging warming effects,” and he continues “A new generation of models is needed
in climate science, impact studies and economics with a stronger focus on lives and
livelihoods, including the risks of large-scale migration and conflicts” (Stern, 2013).
15 Nordhaus (2013) suggests, more specifically, that the damage function needs to be
reexamined carefully and possibly reformulated in cases of higher warming or catas-
trophic damages. In our CoCEB model, an increase in climate-related damages has
the effect of anticipating the crossover time, starting from which the abatement-related
costs start paying off in terms of increased per capita GDP growth.

20 A major drawback of current IAMs is that they mainly focus on mitigation in the en-
ergy sector. For example, the RICE (Regional Dynamic Integrated model of Climate
and the Economy) and DICE (Nordhaus and Boyer, 2000) models consider emissions
from deforestation as exogenous. Nevertheless, GHG emissions from deforestation
and current terrestrial uptake are significant, so including GHG mitigation in the biota
25 sinks has to be considered within IAMs. Several studies provide evidence that forest
carbon sequestration can help reduce atmospheric CO₂ concentration significantly and
could be a cost-efficient way for curbing climate change (e.g. Tavoni et al., 2007; Bosetti
et al., 2011).

In Part 2 of this paper, we report on work along these lines, by studying relevant economic aspects of deforestation control and carbon sequestration in forests, as well as the widespread application of CCS technologies as alternative policy measures for climate change mitigation.

Finally, even though there are several truly coupled IAMs (e.g. Nordhaus and Boyer, 1998; Ambrosi et al., 2003; Stern, 2007), these IAMs disregard variability and represent both climate and the economy as a succession of equilibrium states without endogenous dynamics. This can be overcome by introducing business cycles into the economic module (e.g. Akaev, 2007; Hallegatte et al., 2008) and by taking them into account in considering the impact of both natural, climate-related and purely economic shocks (Hallegatte and Ghil, 2008; Groth et al., 2014).

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**Table 1.** List of variables and parameters and their values used.

Symbol	Meaning	Value	Units	Source
Independent variables				
K	Per capita physical capital		Trillions USD ₁₉₉₀	
H	Per capita human capital		Trillions USD ₁₉₉₀	
T	Average global surface temperatures		Kelvin (K)	
C	Atmospheric CO ₂ concentration		Gt C	
E_Y	Industrial CO ₂ emissions		GtCyr ⁻¹	
Initial (1990) values for independent variables				
k_0	Per capita physical capital-human capital ratio K_0/H_0	8.1	Ratio	Erk et al. (1998)
K_0		0.8344	USD ₁₉₉₀ 10 ⁴	Nordhaus and Boyer (2000)
H_0		0.1039	USD ₁₉₉₀ 10 ⁴	K_0/k_0
T_0		287.77	Kelvin (K)	
C_0		735	Gt C	Nordhaus and Boyer (2000)
E_{Y0}		6	GtCyr ⁻¹	Lenton (2000)
Parameters and other symbols				
Economy module				
n	Population growth rate		%yr ⁻¹	Nordhaus (2013)
L	Human population		Millions	
L_0	1990 world population	5632.7	Millions	Nordhaus and Boyer (2000)
n_0	1990 population growth rate	1.57	%yr ⁻¹	Nordhaus and Boyer (2000)
Λ_L	Population carrying capacity	11 360	Millions	Aral (2013)
A	Total factor productivity	2.9		Greiner and Semmler (2008)
c	Consumption share	80	%yr ⁻¹	Greiner and Semmler (2008)
φ	External effect coefficient	0.1235		
δ_K	Depreciation rate of K	7.5	%yr ⁻¹	Greiner and Semmler (2008)
δ_H	Depreciation rate of H	7.2	%yr ⁻¹	
δ_n	Decline rate of n	2.22	%yr ⁻¹	
α	Capital share	0.35		Nordhaus and Boyer (2000)
τ	Tax rate	20	%yr ⁻¹	Gollin (2002)
τ_b	Abatement share	0; 0.075; 0.11; 0.145	Ratio	Greiner and Semmler (2008)
Damage function				
m_1		0.0067		Roughgarden and Schneider (1999)
χ		2.43		

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Table 1. Continued.

Symbol	Meaning	Value	Units	Source
Climate module (carbon cycle and surface temperature)				
β_2	Part of CO ₂ emissions taken up by oceans and do not enter the atmosphere	0.49		IPCC (2001, p. 39)
μ_o	Rate of CO ₂ absorption from the atmosphere into the ocean	0.0083		Nordhaus (1994a)
\hat{C}	Pre-industrial CO ₂ concentration	596.4	GtC	Wigley (1991)
e_c	Energy intensity		TRF/USD 10 ³ of \bar{Y}	Akaev (2012)
c_c	Carbon intensity of energy		tC TRF ⁻¹	Akaev (2012)
g_{ec}	Growth rate of e_c			
g_{oc}	Growth rate of c_c			
σ	Carbon intensity		tC/USD 10 ³ of \bar{Y} (Ratio)	Nordhaus and Boyer (2000)
g_σ	Rate of decline of σ			
σ_0	1990 level σ	0.274	tC/USD 10 ³ of \bar{Y} (Ratio)	Nordhaus and Boyer (2000)
ψ_0		0.042		Akaev (2012)
α_T	Abatement efficiency	1.8		
r		0.05		Akaev (2012)
$c_{-\infty}$	c_c used before 1990	0.1671	tC TRF ⁻¹	
a_c		0.169		Akaev (2012)
c_h	Earth specific heat capacity	16.7	Wm ⁻² K ⁻¹	Schwartz (2008)
α_T	Planetary/Surface albedo	0.3		McGuffie and Henderson-Sellers (2005)
ε	Emissivity	0.95		McGuffie and Henderson-Sellers (2005)
σ_T	Stefan–Boltzmann constant	5.67×10^{-8}	Wm ⁻² K ⁻⁴	McGuffie and Henderson-Sellers (2005)
τ_a	Infrared transmissivity	0.6526		McGuffie and Henderson-Sellers (2005)
Q	Solar flux	1366	Wm ⁻²	Gueymard (2004)
ξ	T rise absorbed by the oceans	0.23		Greiner and Semmler (2008)
β_1	Feedback effect	3.3		Greiner and Semmler (2008)
\hat{T}	Pre-industrial T	287.17	K	

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Table 2. Target values of key variables for our policy scenarios at year 2100, with $\chi = 2.43$.

τ_b	Emissions E_Y (GtCyr ⁻¹)	CO ₂ C/\hat{C}	Deviation from pre-industrial $T - \hat{T}$ (°C)	Damages (% GDP)	GDP growth g_Y (%yr ⁻¹)
0	29.3	3.1	5.2	26.9	1.1
0.075	11.8	2.1	3.4	11.6	2.1
0.11	5.9	1.7	2.6	6.6	2.2
0.145	2.5	1.5	2.0	3.5	2.0

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Table 3. Per capita abatement costs and damage costs at year 2100, with $\chi = 2.43$.

Abatement share τ_b	% emissions (E_Y) reduction from baseline	Per capita abatement costs (% Y)	Per capita damage costs (% Y)
0	0	0	26.9
0.075	60	1.5	11.6
0.11	80	2.2	6.6
0.145	92	2.9	3.5

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**Table 4.** Comparison between global results of alternative policies.

Global industrial CO ₂ emissions (GtCyr ⁻¹)							
Policy Scenario	1995	2005	2010	2020	2030	2050	2100
CoCEB model: $\tau_b = 0$	7.1	10.8	13.2	19.3	27.0	43.4	29.3
CoCEB model: $\tau_b = 0.075$	6.8	9.2	10.6	13.8	17.0	21.6	11.8
CoCEB model: $\tau_b = 0.11$	6.7	8.6	9.6	11.7	13.5	14.7	5.9
RCP8.5 (Rao and Riahi, 2006; Riahi et al., 2007)	–	8	8.9	11.5	13.8	20.2	28.7
RCP6.0 (Fujino et al., 2006; Hijioka et al., 2008)	–	8	8.5	9	10	13	13.8
RCP4.5 (Smith and Wigley, 2006; Clerke et al., 2007; Wise et al., 2009)	–	8	8.6	9.9	11	11	4.2
Global atmospheric CO ₂ concentration (GtC)							
	1995	2010	2020	2030	2050	2075	2100
CoCEB model: $\tau_b = 0$	743	793	852	939	1206	1612	1842
CoCEB model: $\tau_b = 0.075$	743	785	826	880	1014	1168	1231
CoCEB model: $\tau_b = 0.11$	743	781	816	858	948	1027	1037
RCP8.5 (Riahi et al., 2007)	–	829	886	956	1151	1529	1993
RCP6.0 (Fujino et al., 2006; Hijioka et al., 2008)	–	829	872	914	1017	1218	1427
RCP4.5 (Clerke et al., 2007; Wise et al., 2009)	–	829	875	927	1036	1124	1147

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Table 5. Policy scenario values at year 2100 with $\alpha_\tau = 1.8$, varying m_1 , and χ .

	τ_b	Emissions E_Y (GtCyr ⁻¹)	CO ₂ , C/\bar{C}	Deviation from pre-industrial, $T - \hat{T}$ (°C)	Damages (% GDP)	GDP growth g_Y (%yr ⁻¹)	
$m_1 = 0.0034$ (–50%)	$\chi = 2.34$	0	50.8	3.7	5.9	20.3	1.8
		0.075	16.0	2.2	3.7	7.3	2.5
		0.11	7.3	1.8	2.8	3.8	2.4
		0.145	2.8	1.5	2.1	1.9	2.1
$m_1 = 0.01$ (+50%)		0	20.4	2.8	4.7	30.3	0.7
		0.0175	9.3	2.0	3.2	14.4	1.8
		0.11	5.0	1.7	2.5	8.6	2
		0.145	2.2	1.5	1.9	4.8	1.9
$\chi = 1.215$ (–50%)	$m_1 = 0.0067$	0	99.6	4.5	6.7	6.3	3.6
		0.075	19.1	2.3	3.8	3.3	3.0
		0.11	7.8	1.8	2.8	2.3	2.6
		0.145	2.9	1.5	2.1	1.6	2.2
$\chi = 3.645$ (+50%)		0	6.0	2.1	3.6	41.6	–0.2
		0.075	4.9	1.8	2.8	22.9	1.0
		0.11	3.5	1.6	2.4	13.5	1.6
		0.145	1.9	1.5	1.9	6.6	1.8

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Table 6. Effect of varying α_τ by year 2100; all other parameter values as in Table 1.

	Abatement share τ_b	% reduction of emissions (E_Y) from baseline	Per capita abatement costs (% Y)	Per capita damage costs (% Y)	GDP growth g_Y (% yr^{-1})
Abatement efficiency = 0.9 (–50 %)	0	0	0	26.9	1.1
	0.075	48	1.5	13.6	1.8
	0.11	67	2.2	8.8	1.9
	0.145	81	2.9	5.5	1.8
Abatement efficiency = 2.7 (+50 %)	0	0	0	26.9	1.1
	0.075	71	1.5	9.4	2.3
	0.11	90	2.2	4.4	2.4
	0.145	98	2.9	1.9	2.1

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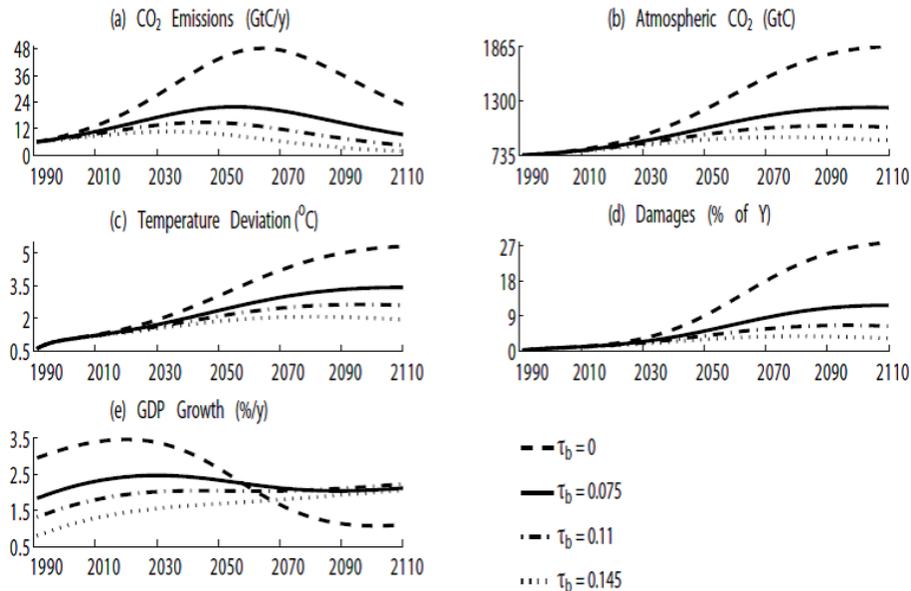


Figure 1. Evolution of several CoCEB model variables in time, for abatement shares τ_b that range from 0.0 (no abatement) to 0.145; see legend for curves, with $\tau_b = 0$ – dashed, $\tau_b = 0.075$ – solid, $\tau_b = 0.11$ – dash-dotted, and $\tau_b = 0.145$ – dotted.

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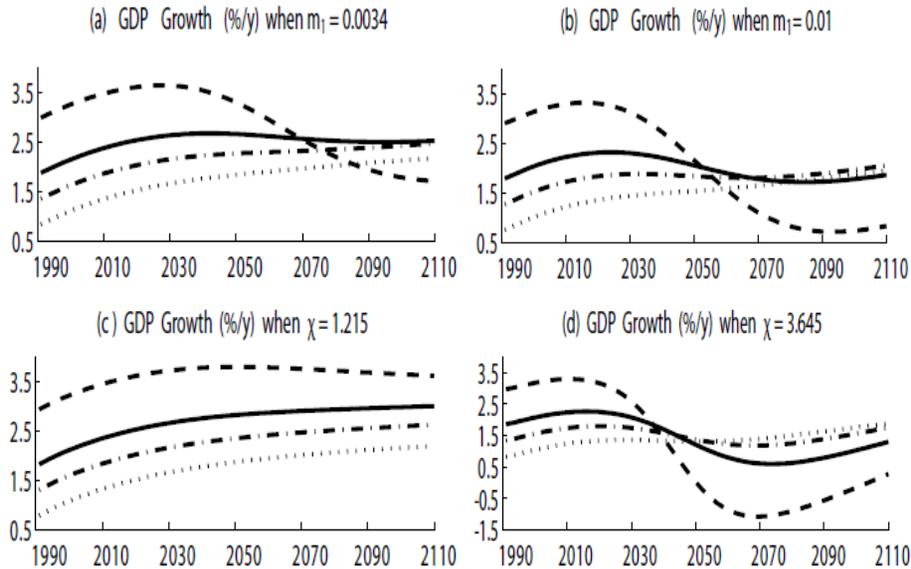


Figure 2. GDP growth over time as a function of abatement share values τ_b between 0.0 and 0.145; see legend for curve identification, while $\alpha_\tau = 1.8$. **(a, b)** m_1 is larger or smaller by 50% than the value in Tables 1–4; **(c, d)** same for the nonlinearity parameter χ .

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